







- Magnetic incremental encoders
- Programmable ppr number
- Zero pulse

- Several configurations available
- Accurate, strong and reliable

Incremental encoders **EP/REP** ppr no. ranges from 8 to 2048. The ppr no. is easily set by the user directly via PC; the programming kit supplied with the encoder includes the USB cable ended with the encoder connector, and the CD with the programming software.

EP/REP operate according to the magnetic principle, and offer excellent performances in terms of *resistance to vibrations and shocks, acceleration, speed and protection.*

The different mechanical versions can meet every type of application requirement; each mechanical type is available with ABS plastic case – series **EP** with push-pull output – or metal case – series **REP** with line driver output.

• Type EP:

ABS plastic case

Push-pull electronic output

7-pin MS connector axial or radial outleti

Type REP

Aluminium case

5 Vdc or 5/28 Vdc line-driver output

12-pin Connei connector axial or radial outlet

MECHANICAL VERSIONS

Series EP/REP521:	Series EP/REP511:	Series EP/REP621:
Round flanged, Ø 58 mm,	Round flanged, Ø 58 mm	Square flanged 63.5 x 63.5 mm
servo coupling	servo coupling	Centering mask Ø 31.75 mm
Ø 50 mm centering mask	Ø 31.75 mm centering mask	Shaft Ø 6, 8, 9.52 or 10 mm
Shaft Ø: 6, 8, 9.52 or 10 mm	Shaft Ø: 6, 8, 9.52 or 10 mm	
Series EP/REP541:	Series EP/REP651:	Series EP/REP411:
Round flange Ø 58 mm, servo coupl.	Square flange 63.5x63.5 mm	Round flanged, Ø 63 mm
Centering mask Ø 36 mm	Centering mask Ø 50 mm	Hollow shaft for direct mounting
3 M4 holes at 120° on Ø 48 mm	Shaft Ø 6, 8, 9.52 or 10 mm	to a motor shaft, hole diameter
Shaft Ø 6, 8, 9.52 or 10 mm		8, 10, 12, 14 or 15 mm
Series EP/REP401:	Series EP/REP471	
Round flange, Ø 58 mm, fixing holes	Round flange, Ø.72 mm, fixing holes	
on Ø 30 mm	on Ø 63.5	
Joint for direct mounting to a motor	Joint for direct mounting to a motor	
shaft diameter 6 8 or 10 mm	shaft diameter 6, 8 or 10 mm	

MECHANICAL & ENVIRONMENTAL SPECIFICATIONS

Materials: case shaft	EP: ABS / REP aluminium Stainless steel AISI 303
Revolutions/minute	6000* continous 10000 temporary *max operating speed with IP65 sealing ring applied on the shaft: 3000
Starting torque	≤0,8 Ncm
Inertia	≤25 g cm ²
Max. load	80N axial/100N radial
• Vibration resistance (10÷2000 Hz)	100 m/sec ²
Shock resistance (11 ms)	50 G
Protection degree	IP64 (optional IP65 with sealing ring)
Operating temperature	0 ÷ 70°C
Stocking temperature	-20 ÷ 80°C



ELECTRICAL & OPERATING SPECIFICATIONS

Pulse code	Incremental
 Pulses/revolution 	8, 10, 16, 20, 25, 32, 40, 50, 64, 80, 100, 125, 128, 200, 250, 256, 400, 500, 512, 1024, 2048
• Zero pulse	1 pulse each revolution
Output signals	Two square waves 90° ±15° out of phase - Zero pulse width: 90°±15°
Electronic output	Push-pull or line driver - Signals protected against short circuits
Supply voltage	5/28 Vdc - Protection against polarity reversal
 Power consumption 	1.2 W
Max. frequency	200 KHz
Connection outlets	MS 7-pin axial or radial connector (push-pull output) or Connei 12-pin axial or radial connector (line driver output)

The programming kit includes: 7 or 12-pin connector + USB cable for encoder to PC connection - CD containing the programming tool -.Minimum system requirements: Windows2000/XP/VISTA



